

Optimal control of fractional Sturm–Liouville wave equations on a star graph

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- 3 Existence of minimizers and optimality conditions

1 Introduction and motivation

Network

Sturm-Liouville Theory

Fractional Calculus

Spectral Theorem

2 Fractional Sturm–Liouville wave equations

3 Existence of minimizers and optimality conditions

1 Introduction and motivation

Network

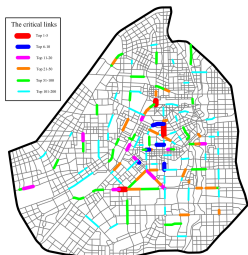
Sturm-Liouville Theory

Fractional Calculus

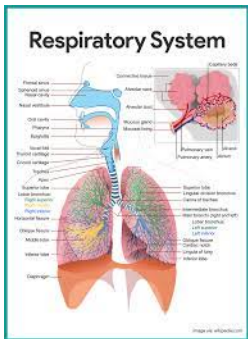
Spectral Theorem

2 Fractional Sturm–Liouville wave equations

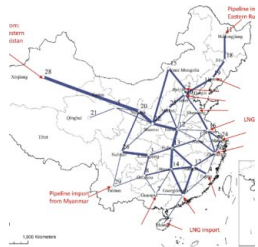
3 Existence of minimizers and optimality conditions



Mynd: Traffic flow network



Mynd: Respiratory system network



Mynd: Gas-pipeline network of China

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A Sturm-Liouville problem is a problem generated by the following equation,

$$-\frac{d}{dx} \left(p(x) \frac{dy}{dx} \right) + l(x)y = \lambda r(x)y.$$

Importance of Sturm-Liouville:

- All second order equation can be transform into a Sturm-Liouville problem
- Under suitable initial and boundary condition, the Sturm-Liouville operator is self-adjoint.

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The fractional calculus theory

- generalizes the classical differential calculus
- takes into account the non-locality and memory effect
- models physical and engineering processes that are found to be best described by fractional differential equations (anomalous diffusion, viscoelastic models, aeroelastic, etc...)

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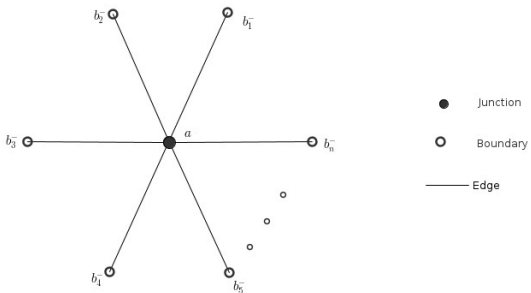
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we consider a network in the form of a star graph



Mynd: Star graph with n edges

We define the spaces

$$H_{a^+}^\alpha(a, b_i) = AC_{a^+}^{\alpha,2} \cap L^2(a, b_i)$$

$$\mathbb{H}_a^\alpha := \prod_{i=1}^n H_{a^+}^\alpha(a, b_i) \quad \mathbb{L}^2 = \prod_{i=1}^n L^2(a, b_i).$$

with the norms

$$\|\rho\|_{\mathbb{L}^2}^2 = \sum_{i=1}^n \|\rho^i\|_{L^2(a, b_i)}^2, \quad \rho = (\rho^i)_i \in \mathbb{L}^2,$$

$$\|\rho\|_{\mathbb{H}_a^\alpha}^2 = \sum_{i=1}^n \|\rho^i\|_{H_{a^+}^\alpha(a, b_i)}^2 := \sum_{i=1}^n \left(\|\rho^i\|_{L^2(a, b_i)}^2 + \|\mathbb{D}_{a^+}^\alpha \rho^i\|_{L^2(a, b_i)}^2 \right).$$

We define the space \mathcal{V}_i by

$$\mathcal{V}_i := \left\{ \rho^j \in H_{a^+}^\alpha(a, b_i) : \mathcal{D}_{b^-}^\alpha(\beta^i \mathbb{D}_{a^+}^\alpha \rho^j) \in H_{b^-}^{1-\alpha}(a, b_i) \right\}$$

$$\mathbb{V} = \left\{ (\rho^i)_i \in \prod_{i=1}^n \mathcal{V}_i : I_{a^+}^{1-\alpha} \rho^i(a^+, \cdot) = I_{a^+}^{1-\alpha} \rho^j(a^+, \cdot), i \neq j, i, j = 1, \dots, n \right. \\ \left. \sum_{i=1}^n \beta^i(a) \mathbb{D}_{a^+}^\alpha \rho^i(a^+, \cdot) = 0 \right\}$$

with the norm $\|\rho\|_{\mathbb{V}} = \|\rho\|_{\mathbb{H}_a^\alpha} \quad \forall \rho = (\rho^i) \in \mathbb{V}.$

For any $\rho, \phi \in \mathbb{V}$, we define the bilinear form $\mathbb{E}(\cdot, \cdot) : \mathbb{V} \times \mathbb{V} \rightarrow \mathbb{R}$ by:

$$\begin{aligned} \mathbb{E}(\rho, \phi) &= \sum_{i=1}^N \int_{Q_i} (\beta^i(x) \mathbb{D}_{a^+}^{\alpha} \phi^i)(x, t) \mathbb{D}_{a^+}^{\alpha} (\rho^i)(x, t) dx dt \\ &\quad + \sum_{i=1}^N \int_{Q_i} q^i(x) \phi^i(x, t) \rho^i(x, t) dx dt, \end{aligned}$$

Assumption

$\beta^i \in \mathcal{C}^1([a, b_i])$, $i = 1, \dots, n$ and $q^i \in \mathcal{C}([a, b_i])$, $i = 1, \dots, n$ such that

$$\begin{aligned} \underline{q}^0 &:= \min_{1 \leq i \leq n} q^i, & \underline{\beta}^0 &:= \min_{1 \leq i \leq n} \beta^i, \\ \bar{q} &:= \max_{1 \leq i \leq n} \|q^i\|_{\infty}, & \bar{\beta} &:= \max_{1 \leq i \leq n} \|\beta^i\|_{\infty} \end{aligned}$$

Then, we define the self adjoint operator \mathcal{A} as follows: For

We define the operator \mathcal{A} as follows: For $\rho = (\rho^i)_i$, we let

$$\mathcal{A}\rho = ((\mathcal{A}\rho)^i)_i = \left(\mathcal{D}_{b_i^-}^\alpha (\beta^i \mathbb{D}_{a^+}^\alpha \rho^i) + q^i \rho^i \right)_i, \quad i = 1, \dots, n. \quad (4)$$

with

$$D(\mathcal{A}) : \{(\rho^i)_i \in \mathbb{V}; I_{a^+}^{1-\alpha} \rho^i(b_i^-) = 0, \quad i = 1, \dots, m, \quad \beta^i(b_i) \mathbb{D}_{a^+}^\alpha \rho^i(b_i^-) = 0, \quad i = m+1, \dots, n\}$$

and $\|\phi\|_{D(\mathcal{A})}^2 := \|\phi\|_{\mathbb{V}}^2$.

- For $1/2 < \alpha < 1$, the embedding $\mathbb{H}_g^\alpha \hookrightarrow \mathbb{L}^2$ is compact.
- \mathcal{A} is a self-adjoint operator.
- $\mathbb{E}(\cdot, \cdot)$ is continuous and coercive on \mathbb{V} .

Conclusion: there exists an orthonormal basis of \mathbb{L}^2 , $(\varphi_n)_n$ consisting of eigenvectors of \mathcal{A} , moreover from the coercivity and the nonnegativity of $\mathbb{E}(\cdot, \cdot)$, the eigenvalues associated to $(\varphi_n)_n$ verifies

$$0 < \lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_n \leq \dots \quad \text{with} \quad \lim_{n \rightarrow \infty} \lambda_n = +\infty.$$

Problem setting

$$\min_{v \in \mathcal{U}_{ad}} \sum_{i=1}^n \left(\frac{1}{2} \int_a^{b_i} |y^i(T) - z_d^{0,i}|^2 dx + \frac{1}{2} \int_a^{b_i} |y_t^i(T) - z_d^{1,i}|^2 dx + \frac{N}{2} \int_a^{b_i} |v_i|^2 dx \right),$$

where $z_d^0 = (z_d^{0,i})_i \in \mathbb{V}$, $z_d^1 = (z_d^{1,i})_i \in \mathbb{L}^2$ and $y = (y^i)_i$ satisfies the following wave equation:

$$\left\{ \begin{array}{ll} y_{tt}^i + \mathcal{D}_{b_i^-}^\alpha (\beta^i \mathbb{D}_{a^+}^\alpha y^i) + q^i y^i & = f^i, & \text{in } (a, b_i) \times (0, T), \quad i = 1, \dots, n, \\ I_{a^+}^{1-\alpha} y^i(a^+) & = I_{a^+}^{1-\alpha} y^j(a^+) & \text{in } (0, T), \quad i \neq j = 1, \dots, n, \\ \sum_{i=1}^n \beta^i(a) \mathbb{D}_{a^+}^\alpha y^i(a^+) & = 0, & \text{in } (0, T), \\ I_{a^+}^{1-\alpha} y^1(b_1^-) & = 0, & \text{in } (0, T), \\ I_{a^+}^{1-\alpha} y^i(b_i^-) & = h_i, & \text{in } (0, T), \quad i = 2, \dots, m, \\ \beta^i(b_i) \mathbb{D}_{a^+}^\alpha y^i(b_i^-) & = g_i, & \text{in } (0, T), \quad i = m+1, \dots, n, \\ y^i(0) & = y^{0,i}, & \text{in } (a, b_i), \quad i = 1, \dots, n, \\ y_t^i(0) & = v_i, & \text{in } (a, b_i), \quad i = 1, \dots, n. \end{array} \right. \quad (5)$$



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We consider the following:

$$\left\{ \begin{array}{ll} y_{tt}^i + \mathcal{D}_{b_i^-}^\alpha (\beta^i \mathbb{D}_{a^+}^\alpha y^i) + q^i y^i & = f^i & \text{in } Q_i, \quad i = 1, \dots, n, \\ I_{a^+}^{1-\alpha} y^i(a^+, \cdot) & = I_{a^+}^{1-\alpha} y^j(a^+, \cdot) & \text{in } (0, T), \quad i \neq j = 1, \dots, n, \\ \sum_{i=1}^n \beta^i(a) \mathbb{D}_{a^+}^\alpha y^i(a^+, \cdot) & = 0 & \text{in } (0, T), \\ I_{a^+}^{1-\alpha} y^i(b_i^-, \cdot) & = 0 & \text{in } (0, T), \quad i = 1, \dots, m \\ \beta^i(b_i) \mathbb{D}_{a^+}^\alpha y^i(b_i^-, \cdot) & = 0 & \text{in } (0, T), \quad i = m+1, \dots, n, \\ y^i(0) & = y^{0,i} & \text{in } (a, b_i), \quad i = 1, \dots, n, \\ y_t^i(0) & = v_i & \text{in } (a, b_i), \quad i = 1, \dots, n, \end{array} \right. \quad (6)$$

where $f = (f^i) \in L^2((0, T); \mathbb{V}^*)$, $y^0 = (y^{0,i}) \in D(\mathcal{A})$,
 $v = (v_i) \in \mathbb{L}^2$.

The Cauchy problem (6) becomes

$$\begin{cases} y_{tt} + \mathcal{A}y &= f(t) & \text{for } t \in (0, T), \\ y(\cdot, 0) &= y^0, \\ y_t(\cdot, 0) &= v, \end{cases} \quad (7)$$

Definition

A function $y = (y^i)$ is said to be a weak solution of (6) in $(0, T)$, $T > 0$, if the following assertions hold.

- Regularity: $y \in C^1([0, T]; \mathbb{L}^2) \cap C([0, T]; D(\mathcal{A}))$
- Initial condition: $y^i(\cdot, 0) = y^{i,0}$ in (a, b_i) , $i = 1, \dots, n$
 $y_t^i(\cdot, 0) = v_i$ in (a, b_i) , $i = 1, \dots, n$
- Variational identity:
 $\langle y_{tt}, \zeta \rangle_{\mathbb{V}^*, \mathbb{V}} + \mathbb{E}(y(t, \cdot), \zeta) = \langle f(t, \cdot), \varphi \rangle_{\mathbb{V}^*, \mathbb{V}}$ for every $\varphi \in D(\mathcal{A})$, and a.e. $t \in (0, T)$.

Theorem

Let $1/2 < \alpha < 1$, $f \in L^2((0, T); \mathbb{V}^*)$ and $y^0 \in D(\mathcal{A})$, $v \in \mathbb{L}^2$, the system (6) has a unique weak solution $y = (y^i)$ given by

$$y(t, \cdot) = \sum_{n=1}^{\infty} \left\{ \frac{1}{\sqrt{\mu_n}} \langle v, \zeta_n \rangle_{\mathbb{L}^2} \sin(\sqrt{\mu_n} t) + \langle y^0, \zeta_n \rangle_{\mathbb{L}^2} \cos(\sqrt{\mu_n} t) + \frac{1}{\sqrt{\mu_n}} \int_0^t \sin(\sqrt{\mu_n}(t-s)) \langle f(s), \zeta_n \rangle_{\mathbb{V}^*, \mathbb{V}} ds \right\} \zeta_n. \quad (8)$$

Moreover,

$$\frac{1}{2} \|y_t\|_{C([0, T]; \mathbb{L}^2)}^2 \leq 2T \|f\|_{L^2((0, T); \mathbb{L}^2)}^2 + \|v\|_{\mathbb{L}^2}^2 + \max(\bar{\beta}, \bar{q}) \|y^0\|_{\mathbb{H}_g^\alpha}^2 \quad (9a)$$

$$\|y\|_{C([0, T]; \mathbb{H}_g^\alpha)}^2 \leq \frac{2}{\min(\underline{\beta}^0, \underline{q}^0)} (2T \|f\|_{L^2((0, T); \mathbb{L}^2)}^2 + \|v\|_{\mathbb{L}^2}^2 + \max(\bar{\beta}, \bar{q}) \|y^0\|_{\mathbb{H}_g^\alpha}^2) \quad (9b)$$

steps of the prove

- Multiply equation (7) by φ_n to obtain

$$\begin{cases} \frac{\partial^2}{\partial t^2} y_n(t) + \lambda_n y_n(t) = f_n(t) & \text{for } t \in (0, T), \\ y_n(0) = y_n^0, \\ y_n'(0) = v_n, \end{cases} \quad (10)$$

where

$y_n(t) = (y(t), \varphi_n)_{\mathbb{L}^2}$, $f_n(t) = \langle f(t), \varphi_n \rangle_{\mathbb{V}^*, \mathbb{V}}$, $y_n^0 = (y^0, \varphi_n)_{\mathbb{L}^2}$,
and $v_n = (v, \varphi_n)_{\mathbb{L}^2}$

- Take the Laplace transform of the equation (10).
- Using the Laplace transforms of cos, sin and convolution

functions, recover y_n . then write $y(t) = \sum_{n=1}^{\infty} y_n(t) \varphi_n$.

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In what follows, we shall transform that problem into an homogeneous type problem.

Let $(g_i)_{i=2\dots m}$ and $(h_i)_{i=m+1\dots n} \in H^2(0, T)$ be such that $h_i(0) = g_i(0) = 0$, $i = 1, \dots, n$, we set

$$\|\bar{g}\|_{C([0, T])} = \max_{2 \leq i \leq m} \|g_i\|_{C([0, T])}, \quad \|\bar{h}\|_{C([0, T])} = \max_{m+1 \leq i \leq n} \|h_i\|_{C([0, T])} \quad (11a)$$

$$\|\bar{g}_t\|_{C([0, T])} = \max_{2 \leq i \leq m} \|g_i'\|_{C([0, T])}, \quad \|\bar{h}_t\|_{C([0, T])} = \max_{m+1 \leq i \leq n} \|h_i'\|_{C([0, T])} \quad (11b)$$

We consider the function $w = (w^i)_{i=1, \dots, n}$, where w^i are giving by :

$$w^i(x, t) = \begin{cases} 0 & i = 1 \\ \frac{2g_i(t)}{\Gamma(\alpha + 2)(b_i - a)^2} (x - a)^{\alpha+1} & i = 2, \dots, m \\ \frac{h_i(t)}{\Gamma(\alpha + 2)\beta^i(b_i)(b_i - a)} (x - a)^{\alpha+1} & i = m + 1, \dots, n. \end{cases} \quad (12)$$

Lemma

Assume that Assumption 1 holds. Let $(g_i)_{i=2\dots m} \in (H^2(0, T))^{m-1}$ and $(h_i)_{i=m+1\dots n} \in (H^2(0, T))^{n-m}$ be such that (11) holds. Let also $w = (w^i)$ be defined as in (12). Then we have that w^i , $\mathcal{D}_{b_i^-}^\alpha (\beta^i \mathbb{D}_{a^+}^\alpha w^i) \in L^2(Q_i)$, $w_t^i \in C([0, T]; L^2(a, b_i))$ and $w_{tt}^i \in L^2(Q_i)$.

Moreover,

$$\sup_{t \in [0, T]} \|w(t)\|_{\mathbb{H}_a^\alpha}^2 \leq C(\alpha, \underline{b}, \bar{b}, \underline{\beta}^0, n) \left(\|\bar{g}\|_{C([0, T])}^2 + \|\bar{h}\|_{C([0, T])}^2 \right), \quad (13a)$$

$$\|w_t(0)\|_{\mathbb{L}^2}^2 \leq C(\alpha, \bar{b}, \underline{\beta}^0, n) \left(\|\bar{g}_t\|_{C([0, T])}^2 + \|\bar{h}_t\|_{C([0, T])}^2 \right), \quad (13b)$$

where $\bar{b} = \max_{1 \leq i \leq n} (b_i)$ and $\underline{b} = \min_{1 \leq i \leq n} (b_i)$.

and setting $z = (z^i)_{i=1, \dots, n}$ where $z^i(x, t) = y^i(x, t) - w^i(x, t)$, it follows that z satisfies the homogeneous system

$$\left\{ \begin{array}{ll} z_{tt}^i + \mathcal{D}_{b_i^-}^\alpha (\beta^i \mathbb{D}_{a^+}^\alpha z^i) + q^i z^i & = \tilde{f}^i & \text{in } Q_i, i = 1, \dots, n, \\ I_{a^+}^{1-\alpha} z^i(a^+, \cdot) & = I_{a^+}^{1-\alpha} z^j(a^+, \cdot) & \text{in } (0, T), i \neq j = 1, \dots, n, \\ \sum_{i=1}^n \beta^i(a) \mathbb{D}_{a^+}^\alpha z^i(a^+, \cdot) & = 0 & \text{in } (0, T), \\ I_{a^+}^{1-\alpha} z^1(b_1^-, \cdot) & = 0 & \text{in } (0, T), \\ I_{a^+}^{1-\alpha} z^i(b_i^-, \cdot) & = 0 & \text{in } (0, T), i = 2, \dots, m, \\ \beta^i(b_i) \mathbb{D}_{a^+}^\alpha z^i(b_i^-, \cdot) & = 0 & \text{in } (0, T), i = m + 1, \dots, n, \\ z^i(\cdot, 0) & = y^{0,i} & \text{in } (a, b_i), i = 1, \dots, n, \\ z_t^i(\cdot, 0) & = \tilde{v}_i & \text{in } (a, b_i), i = 1, \dots, n, \end{array} \right. \quad (14)$$

where $\tilde{f}^i \in L^2(Q_i)$ and $\tilde{v}_i \in L^2(a, b_i)$ are given by

$$\tilde{f}^i = f^i - w_{tt}^i - \mathcal{D}_{b_i^-}^\alpha (\beta^i \mathbb{D}_{a^+}^\alpha w^i) - q^i w^i, i = 1, \dots, n, \quad (15a)$$

$$\tilde{v}_i = v_i - w_t^i(\cdot, 0), \quad i = 1, \dots, n. \quad (15b)$$

Theorem

Let $1/2 < \alpha < 1$, $f \in L^2(0, T; \mathbb{L}^2)$, $(g_i)_{i=2 \dots m} \in (H^2(0, T))^{m-1}$ and $(h_i)_{i=m+1 \dots n} \in (H^2(0, T))^{n-m}$ be such that $g_i(0) = h_i(0) = 0$, $i = 1, \dots, n$, $y^0 = (y^{0,i}) \in D(\mathcal{A})$ and $v = (v_i) \in \mathbb{L}^2$, then the problem (5) admit a unique weak solution $y = (y^i) \in \mathcal{C}([0, T], \mathbb{V}) \cap \mathcal{C}^1([0, T], \mathbb{L}^2)$ given by

$$y(x, t) = \sum_{n=1}^{\infty} \left\{ \frac{\tilde{v}_n}{\sqrt{\mu_n}} \sin(\sqrt{\mu_n}t) + y_n^0 \cos(\sqrt{\mu_n}t) + \frac{1}{\sqrt{\mu_n}} \int_0^t \sin(\sqrt{\mu_n}(t-s)) \tilde{f}_n(s) ds \right\} \zeta_n + w(x, t),$$

Moreover, there exist $\Delta_1, \Delta_2 = C(\alpha, \bar{b}, \underline{b}, \bar{\beta}, \bar{q}, \underline{\beta}^0, n) > 0$ such that

$$\begin{aligned} \|y\|_{C([0, T]; \mathbb{H}_\alpha^\alpha)} &\leq \Delta_1 \left(\|f\|_{L^2((0, T); \mathbb{L}^2)}^2 + \|v\|_{\mathbb{L}^2}^2 + \|y^0\|_{\mathbb{H}_\alpha^\alpha}^2 + \|\bar{g}\|_{C([0, T])}^2 \right. \\ &\quad \left. + \|\bar{h}\|_{C([0, T])}^2 + \|\bar{g}_t\|_{C([0, T])}^2 + \|\bar{h}_t\|_{C([0, T])}^2 \right) \end{aligned} \quad (16a)$$

$$\begin{aligned} \|y'\|_{C([0, T], \mathbb{L}^2)} &\leq \Delta_2 \left(\|f\|_{L^2((0, T); \mathbb{L}^2)}^2 + \|v\|_{\mathbb{L}^2}^2 + \|y^0\|_{\mathbb{H}_\alpha^\alpha}^2 + \|\bar{g}\|_{C([0, T])}^2 \right. \\ &\quad \left. + \|\bar{h}\|_{C([0, T])}^2 + \|\bar{g}_t\|_{C([0, T])}^2 + \|\bar{h}_t\|_{C([0, T])}^2 \right) \end{aligned} \quad (16b)$$

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characterization of the optimal control.

We are interested in solving the following optimal control problem:

$$\min_{v \in \mathcal{U}_{ad}} \mathcal{J}(v), \quad (17)$$

where

$$\mathcal{J}(v) := \frac{1}{2} \|y(v; T) - z_d^0\|_{\mathbb{L}^2}^2 + \frac{1}{2} \|y_t(v; T) - z_d^1\|_{\mathbb{L}^2}^2 + \frac{N}{2} \|v\|_{\mathbb{L}^2}^2. \quad (18)$$

We have the following existence result of optimal controls.

Theorem

Let $1/2 < \alpha < 1$. Let $q^i \in \mathcal{C}(a, b_i)$ and $\beta^i \in \mathcal{C}^1([a, b_i])$ satisfy Assumption 1. Then, there exists a unique solution $\hat{u} \in \mathcal{U}_{ad}$ of the optimal control problem (17)-(18).

steps of the proof

- We write

$$\begin{aligned} \mathcal{J}(v) = & \frac{1}{2}\pi(v, v) - L(v) \\ & + \frac{1}{2} \left\| y(0; T) - z_d^0 \right\|_{\mathbb{L}^2}^2 + \frac{1}{2} \left\| y_t(0; T) - z_d^1 \right\|_{\mathbb{L}^2}^2 \end{aligned} \quad (19)$$

- We show that $\pi(\cdot, \cdot)$ symmetric bilinear continuous and coercive functional and that $L(\cdot)$ is a continuous linear functional.
- We conclude using Lax-Milgram Theorem that there exists a unique $u \in \mathcal{U}_{ad}$ that minimizes \mathcal{J} .

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Theorem

Let $1/2 < \alpha < 1$. Let $q^i \in C([a, b_i])$ and $\beta^i \in C^1([a, b_i])$ satisfy Assumption 1. Let $u = (u_i)_i \in \mathcal{U}_{ad}$ be the optimal control for the minimization problem (17)-(18). Then, there exists a unique $p \in L^2((0, T); \mathbb{V}) \cap C^1([0, T]; \mathbb{L}^2)$ such that the triple (\hat{y}, u, p) satisfies

$$\left\{ \begin{array}{ll} \hat{y}_{tt} + \mathcal{D}_{b_i^-}^{\alpha}(\beta^i \mathbb{D}_{a^+}^{\alpha} \hat{y}^i) + q^i \hat{y}^i & = f^i, & \text{in } Q_i, i = 1, \dots, n, \\ I_{a^+}^{1-\alpha} \hat{y}^i(a^+, \cdot) & = I_{a^+}^{1-\alpha} \hat{y}^j(a^+, \cdot) & \text{in } (0, T), i \neq j = 1, \dots, n, \\ \sum_{i=1} \beta^i(a) \mathbb{D}_{a^+}^{\alpha} \hat{y}^i(a^+, \cdot) & = 0, & \text{in } (0, T), \\ I_{a^+}^{1-\alpha} \hat{y}^1(b_1^-, \cdot) & = 0, & \text{in } (0, T), \\ I_{a^+}^{1-\alpha} \hat{y}^i(b_i^-, \cdot) & = g^i, & \text{in } (0, T), i = 2, \dots, m \\ \beta^i(b_i) \mathbb{D}_{a^+}^{\alpha} \hat{y}^i(b_i^-, \cdot) & = h_i, & \text{in } (0, T), i = m+1, \dots, n, \\ \hat{y}^i(\cdot, 0) & = y^{0,i}, & \text{in } (a, b_i), i = 1, \dots, n, \\ \hat{y}_t^i(\cdot, 0) & = u^i, & \text{in } (a, b_i), i = 1, \dots, n, \end{array} \right. \quad (20)$$

and

$$\left\{ \begin{array}{ll} p_{tt}^i + \mathcal{D}_{b_i^-}^\alpha (\beta^i \mathbb{D}_{a^+}^\alpha p^i) + q^i p^i & = 0, & \text{in } Q_i, i = 1, \dots, n, \\ I_{a^+}^{1-\alpha} p^i(a^+, \cdot) & = I_{a^+}^{1-\alpha} p^j(a^+, \cdot) & \text{in } (0, T), i \neq j = 1, \dots, n, \\ \sum_{i=1}^n \beta^i(a) \mathbb{D}_{a^+}^\alpha p^i(a^+, \cdot) & = 0, & \text{in } (0, T), \\ I_{a^+}^{1-\alpha} p^i(b_i^-, \cdot) & = 0, & \text{in } (0, T), i = 1, \dots, m \\ \beta^i(b_i) \mathbb{D}_{a^+}^\alpha p^i(b_i^-, \cdot) & = 0, & \text{in } (0, T), i = m + 1, \dots, n, \\ p^i(\cdot, T) & = \hat{y}_t^i(\cdot, T) - z_d^{1,i} & \text{in } (a, b), i = 1, \dots, n \\ p_t(\cdot, T) & = -(\hat{y}^i(\cdot, T) - z_d^{0,i}) & \text{in } (a, b_i), i = 1, \dots, n \end{array} \right. \quad (21)$$

and

$$\sum_{i=1}^n \int_a^{b_i} (u_i + p^i(\cdot, 0)) (v_i - u_i) dx \geq 0 \quad (22)$$

for all $v = (v_i)_i \in \mathcal{U}_{ad}$.

steps of the proof

- We write the Euler-Lagrange first order optimality condition for u :

$$\lim_{\theta \rightarrow 0} \frac{\mathcal{J}(u + \theta(v - u)) - \mathcal{J}(u)}{\theta} \geq 0, \quad \forall v \in \mathcal{U}_{ad}, \quad (23)$$

- it implies

$$\langle z(v - u; T), y(u; T) - z_d^0 \rangle_{\mathbb{L}^2} + \langle z_t(v - u; T), y_t(u; T) - z_d^1 \rangle_{\mathbb{L}^2} + N(u, v - u)_{\mathbb{L}^2} \geq 0, \quad \forall v \in \mathcal{U}_{ad}, \quad (24)$$

where $z = z(v - u)$ is the solution of

$$\begin{cases} z_{tt} + \mathcal{A}y &= 0 & \text{for } t \in (0, T), \\ z(\cdot, 0) &= 0, \\ z_t(\cdot, 0) &= v - u, \end{cases} \quad (25)$$

- We then interpret (24), by multiplying (25) by p solution of (21), to get equation (22).

- 1 Introduction and motivation
- 2 Fractional Sturm–Liouville wave equations
- 3 Existence of minimizers and optimality conditions

- we show the existence and uniqueness of solution of a Sturm–Liouville wave equation on a star graph
- we show the existence and uniqueness of the minimizer of the cost function.
- we assume that $1/2 < \alpha \leq 1$.

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Thanks for your attention