

Modelisation and optimal control for tumor growth models

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Outline

Introduction

- Motivation and Objectives
- Theoretical Results
- Numerical Results
- Conclusion and perspective

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- ◊ Gliomas are very common and invasive brain tumors.
- ◊ Lactate is considered an important hallmark of glioma development.

- Related Literature (tumor growth):
 - Math modeling of tumor growth (glioma) : P. Tracqui (1995), K.R. Swanson, J.D. Murray, E.C. Alvord, E. Mandonnet, R. Guillevin, ...
 - Math modeling of tumor growth and chemotherapy: J.D. Murray, E.C. Alvord, K.R. Swanson, G. Powathil, M. Kohandel, V. Calvez, E. Grenier, H. Garcke, K. Lam, E. Rocca...

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Proposed model:

$$\partial_t \varphi + \alpha \Delta^2 \varphi - \Delta f(\varphi) + (1 - \omega) \frac{k(u)\varphi}{k' + |\varphi|} = J(u)$$
(1)

$$\partial_t u - div(D(x)\nabla u) = (a(\varphi) - v)u(1 - \frac{u}{N}) - uP(\varphi)$$
(2)

where φ is the lactate concentration, u is the tumor density, ω and v represent treatments (chemotherapy).

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Motivation and Objectives

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- Simulate the evolution of the tumor and lactates and optimize the dose of treatments to be administered to the patient to reduce them.

- Take into account in the mathematical model the link between the evolution of lactate and tumor cell levels.
- Compare and calibrate the mathematical model to medical data.
- Simulate the evolution of the tumor and lactates and optimize the dose of treatments to be administered to the patient to reduce them.
- Utilization of the lactate equation:

$$\partial_t \varphi + \alpha \Delta^2 \varphi - \Delta f(\varphi) + (1 - \omega) \frac{k\varphi}{k' + |\varphi|} = J \quad \text{in } \Omega \times (0, T],$$
 (3)

$$\frac{\partial \varphi}{\partial \nu} = \frac{\partial \Delta \varphi}{\partial \nu} = 0$$
 on $\partial \Omega$ (4)

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$$\varphi|_{t=0} = \varphi_0 \tag{5}$$

H.Raad, L.Cherfils, C.Allery, R. Guillevin. Optimal control of a model for brain lactate kinetics, Asymptotic Analysis, pp. 1–32, 2023.

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$$\mathcal{J}(\varphi,\omega) = \frac{1}{2} \int_0^T \int_\Omega \left(\varphi - \widehat{\varphi}\right)^2 d\mathsf{x} dt + \frac{1}{2} \int_\Omega \left(\varphi(T) - \widehat{\varphi}(T)\right)^2 d\mathsf{x} + \frac{\beta}{2} \int_0^T \int_\Omega \omega^2 d\mathsf{x} dt.$$

where $\widehat{\varphi}$ is the piecewise continuous target function.

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Fig.1: Illustration of the optimization problem to be solved.

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Fig.1: Illustration of the optimization problem to be solved.

- This work consists in two parts:
 - Theoretical part: propose a model and study the well-posed character of the equations.
 - ♦ Numerical part: identify for each patient the parameters (k, k', J...)involved in the equations and optimize the treatment parameters ω and

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Notations

$$\diamond < .> = \frac{1}{Vol(\Omega)} \int_{\Omega} .dx$$
, being understood that, if
 $\varphi \in H^{-1}(\Omega) = H^{1}(\Omega)'$, then $\langle \varphi \rangle = \frac{1}{Vol(\Omega)} \langle \varphi, 1 \rangle_{H^{-1}(\Omega), H^{1}(\Omega)}$.
We also set, whenever this makes sense, $\overline{\varphi} = \varphi - \langle \varphi \rangle$.

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$$\diamond \ \sigma(s) = \frac{ks}{2} \text{ is of class } C^{1} \text{ with } \sigma'(s) = \frac{kk'}{2} \text{ so that } \sigma \text{ is } \varphi$$

◇
$$g(s) = \frac{kS}{k' + |s|}$$
 is of class C^1 , with $g'(s) = \frac{kR}{(k' + |s|)^2}$, so that g is (strictly) monotone increasing and maps \mathbb{R} onto $[-k, k]$.

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 $\diamond g(s) = \frac{ks}{k' + |s|}$ is of class C^{1} , with $g'(s) = \frac{kk'}{(k' + |s|)^{2}}$, so that g is (strictly) monotone increasing and maps \mathbb{R} onto $[-k, k]$.
 $\diamond \mathcal{U}_{ad} = \{\omega \in L^{\infty}(\Omega \times [0, T]) : 0 \le \omega \le 1\}$

 $\diamond f$ is a nonlinear term of class C^{∞} and satisfies

$$f'\geq -c_0,\quad c_0>0.$$

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 \diamond The constants k, k', α and J are positive.

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◊ Existence and uniqueness of the Cahn-Hilliard problem.

Theorem

We assume that φ_0 is given such that $\varphi_0 \in H^1(\Omega)$. Then (3)-(5) has a unique weak solution φ , such that $\varphi \in L^{\infty}([0, T], H^1(\Omega)) \cap C([0, T]; H^1(\Omega)) \cap L^2(0, T; H^3(\Omega))$ and $\frac{\partial \varphi}{\partial t} \in L^2([0, T], H^{-1}(\Omega)) \ \forall T > 0.$

Remark:

 \diamond We can rewrite (3)-(5) in the equivalent form

$$\partial_t \varphi - \Delta \mu + (1 - \omega)g(\varphi) = J \quad \text{in } \Omega \times (0, T],$$
 (6)

$$\mu = -\alpha \Delta \varphi + f(\varphi) \quad \text{in } \Omega \times (0, T], \tag{7}$$

$$\frac{\partial \varphi}{\partial \nu} = \frac{\partial \mu}{\partial \nu} = 0 \quad \text{on } \partial \Omega \times (0, T]$$
 (8)

$$\varphi_{|t=0} = \varphi_0. \tag{9}$$

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◊ Let us define the control-to-state operator S:

$$\omega \in \mathcal{U}_{ad} \mapsto \mathcal{S}(\omega) = (\varphi, \mu)$$

where (φ, μ) is the unique weak solution to the equivalent form with initial data $(\varphi_0 \text{ and parameter } \omega)$ over [0, T].

 Existence and uniqueness of the linearized problem and the adjoint problem.

Theorem

For any $\omega \in U_{ad}$, there exists a unique (ξ, π) associated to $S(\omega) = (\varphi, \mu)$ solution of the adjoint problem with

$$\xi \in L^2(0, \tau^*; H^2(\Omega)) \cap H^1(0, \tau^*; (H^2(\Omega))') \cap C^0([0, \tau^*]; L^2(\Omega))$$

 $\pi \in L^2(0, \tau^*; L^2(\Omega))$
satisfying

$$-\langle \partial_t \xi, p \rangle_{H^{-2}, H^2} + \alpha \int_{\Omega} \pi \Delta p \, dx + (1 - \omega^*) g'(\varphi^*) \xi p \, dx$$
$$- \int_{\Omega} \left(f'(\varphi^*) \pi p + (\varphi^* - \hat{\varphi}) p + \frac{1}{r} \chi_{[\tau^* - r, \tau^*]}(t) (\varphi^* - \hat{\varphi}) p \right) dx = 0$$
$$\int_{\Omega} \pi q dx + \int_{\Omega} \nabla \xi \nabla q dx = 0$$

for a.e. $t \in (0, \tau^*)$ and $\forall q \in H^1(\Omega)$ and $p \in H^2(\Omega)$.

Existence of a minimizer for the objective functional.

Theorem

Let $\omega \in U_{ad}$ and $\tau \in (0, T]$ and let φ be a solution of (3) corresponding to ω .

Then, there exists $\omega^* \in \mathcal{U}_{ad}$ and $\tau^* \in (0, T]$ such that:

$$\inf_{(\omega,\tau)\in\mathcal{U}_{ad}\times(0,T]}\mathcal{J}(\varphi,\omega,\tau)=\mathcal{J}(\varphi^*,\omega^*,\tau^*)$$

where φ^* is a solution of (3) corresponding to ω^*

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- Fréchet differentiability of the functional with respect to time.
- ♦ Simplification of the first-order optimality condition.

Remark: We could also have put the control function on J instead of k, meaning this time that the treatment inhibits the lactate production in the tumor cells.

The equation then reads:

$$\partial_t \varphi + \alpha \Delta^2 \varphi - \Delta f(\varphi) + g(\varphi) = (1 - \omega) J \text{ in } \Omega \times (0, T],$$

 $\frac{\partial \varphi}{\partial \nu} = \frac{\partial \Delta \varphi}{\partial \nu} = 0 \text{ on } \partial \Omega$
 $\varphi_{|t=0} = \varphi_0$

We can prove similar results with minor modifications.

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Numerical Results

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 \diamond we aimed to identify the patient parameters k, k' and J from the medical data.

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- we aimed to identify the patient parameters k, k' and J from the medical data.
- o we used the following ordinary differential equation:

$$\partial_t \varphi + \frac{k\varphi}{k' + \varphi} = \mathbf{J}$$

 $\varphi :$ the concentration of lactate

- k: the maximum transport speed between blood and cell.
- k': the modified positive Michaelis-Menten constant.
- J: the phenomena of lactate production and consumption.

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The evolution of lactate levels over the years.

Fig.2 : Medical data from the University Hospital of Poitiers

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The parameters of these two patients were identified for the both phases.

Patient 1:

For the stable tumor phase we obtained $J_1 = 0.726 \ mM/month$, $k_1 = 1,122 \ mM/month$ and $k' = 1.31 \ mM$. For the evolving tumor phase we obtained $J_2 = 2.05$, $k_2 = 2.097$ and

For the evolving tumor phase we obtained $J_2 = 2.05$, $k_2 = 2.097$ and k' = 1.31.



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Patient 3:

For the stable tumor phase we obtained $J_1 = 2.034 \ mM/month$, $k_1 = 2.292 \ mM/month$ and $k' = 0.515 \ mM$. For the evolving tumor phase we obtained $J_2 = 3.44$, $k_2 = 3.87$ and k' = 0.515.



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◊ Ω is an ellipse parametrized by x = 6cosθ and y = 8sinθ, with θ ∈ [0, 2π]

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- ◊ Ω is an ellipse parametrized by x = 6cosθ and y = 8sinθ, with θ ∈ [0, 2π]
- \diamond The initial tumor area is delimited by a circle of radius r = 0.8.

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- ◊ Ω is an ellipse parametrized by x = 6cosθ and y = 8sinθ, with θ ∈ [0, 2π]
- \diamond The initial tumor area is delimited by a circle of radius r = 0.8.
- $\diamond\,$ The target value of the lactate concentration is taken as $\hat{\varphi}=$ 0.8 mM.

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- ◊ Ω is an ellipse parametrized by x = 6cosθ and y = 8sinθ, with θ ∈ [0, 2π]
- \diamond The initial tumor area is delimited by a circle of radius r = 0.8.
- $\diamond\,$ The target value of the lactate concentration is taken as $\hat{\varphi}=$ 0.8 mM.
- $\diamond \ lpha = 0.01$ and the potential f(arphi) = 0.002 arphi(arphi-5)(arphi-10).

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\diamond With the algorithm we obtain $\omega^* = 0.804$ (patient 1).



Fig.5a : Spatial distribution of lactate levels without treatment at T=6 months.



Fig.5b : Spatial distribution of lactate levels with treatment at T=6 months.

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\diamond With the algorithm we obtain $\omega^* = 0.322$ (patient 3).



Fig.6a : Spatial distribution of lactate levels without treatment at T=6 months.



Fig.6b : Spatial distribution of lactate levels with treatment at T=6 months.

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Fig.7 : Temporal evolution of lactate levels in the tumor area.

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If we compare the lactate level inside the tumor area, we see that it decreased with treatment while it increased without treatment.

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		-1.57		

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Conclusion and perspective

Outline

- Introduction
- Motivation and Objectives
- Theoretical Results
- Numerical Results
- Conclusion and perspective

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Conclusion and perspective

 The mathematical modeling and the results are encouraging and consistent with the medical knowledge.

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Conclusion and perspective

- The mathematical modeling and the results are encouraging and consistent with the medical knowledge.
- ♦ Our aim now is to study the coupling with the tumor equation (2) : $\begin{cases}
 \partial_t \varphi + \alpha \Delta^2 \varphi - \Delta f(\varphi) + \frac{k(u)\varphi}{k' + |\varphi|} = (1 - \omega)J(u) \\
 \partial_t u - div(D(x)\nabla u) = (a(\varphi) - v)u(1 - \frac{u}{N}) - uP(\varphi)
 \end{cases}$

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Thank you for your attention

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